

MM-400

Welcome to the Neobotix Documentation for MM-400



The mobile manipulator MM-400 combines the basic platform [MP-400](#) and a lightweight arm from [Pilz](#) to a very compact and flexible robot system for research. This makes the MM-400 ideal for applications in very limited spaces where other platforms can no longer manoeuvre.

The Pilz lightweight arm can be individually configured to meet the exact requirements of the project in question.

The control of the platform with localisation, planning and path interpolation is based on the proven software PlatformCtrl from Neobotix or on ROS. The Pilz lightweight arm can also be controlled by ROS.

Technical Details

Please take a look at our [Website](#)

Contact information

For more information please visit our website at www.neobotix-robots.com. If you have any questions, just get in touch with us:

- General information: <http://www.neobotix-robots.com/company-contact.html>
- ROS related questions: ros@neobotix.de