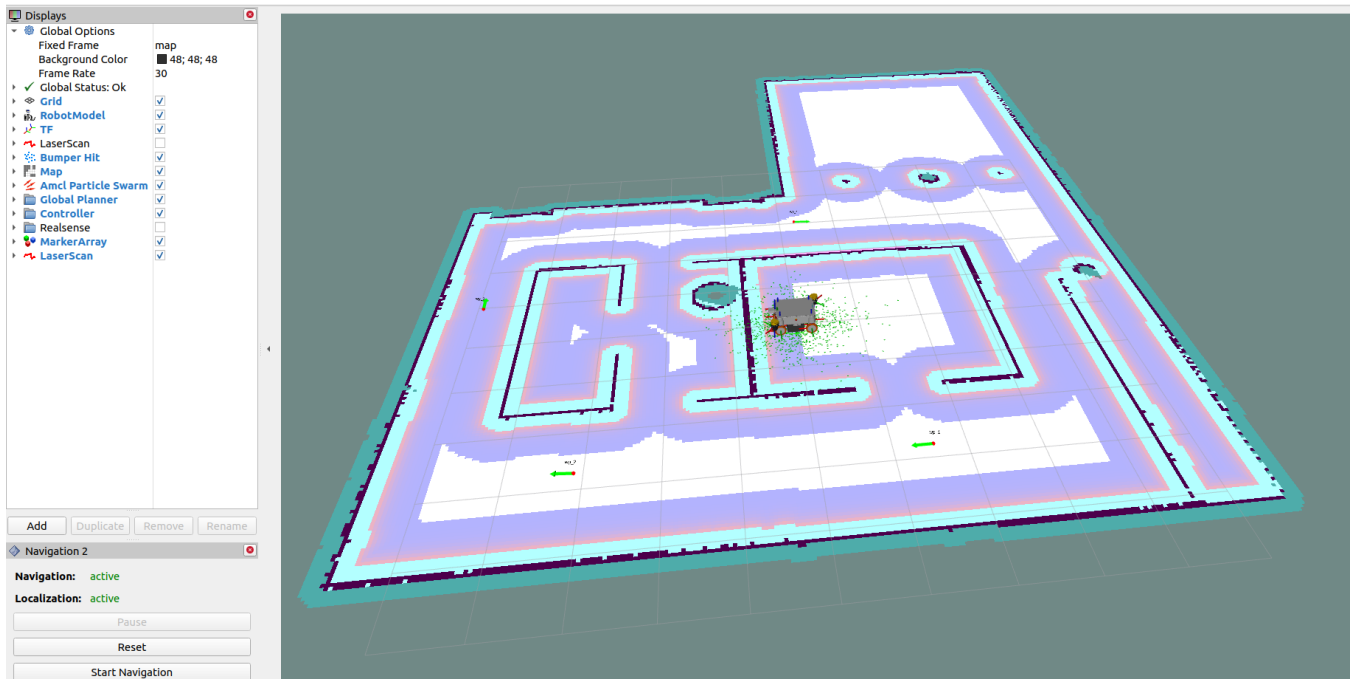


ROS 2-Simulation

Welcome to the ROS 2-Simulation Documentation



The simulation package `neo_simulation2`, comes along with all the new ROS 2 features. Like its predecessor, `neo_simulation2` package is fully equipped with all the Neobotix robots that is available in the market. By combining the novelty of ROS 2 and the state-of-the-art Neobotix platforms would allow the users to learn and develop various reliable and robust application that caters their needs in both the research and as well as in industries.

There are two ways you can use our simulation packages:

ROS Developmental studio



Installation on Ubuntu

